# Implementation with a Sympathizer

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Can a planner implement a given goal without knowing individuals' state-contingent preferences/choices?

That is, can we attain implementation of

- a goal that depends on states of the economy, while
- the planner is completely ignorant of how states of the economy and individuals' preferences are associated?

# The Framework

- A planner aims to implement a goal that depends on states of the economy.
- Each state of the economy is associated with individuals' underlying preferences that we refer to as *payoff-relevant states*.
- The planner is completely ignorant of the association between the states of the economy and the payoff-relevant states.

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For example, the planner could be an implementation consulting agency (e.g., McKinsey Implementation (McKinsey, 2018)) that is tasked to

 elicit information about the details of a client firm and to implement a given policy contingent on this information.

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Alternatively, the planner could be a court-appointed trustee authorized to run a company during its bankruptcy proceedings.

# The Framework

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- Each state of the economy is associated with individuals' underlying preferences that we refer to as *payoff-relevant states*.
- The planner is completely ignorant of the association between the states of the economy and the payoff-relevant states.
- The planner can be viewed to face an extreme form of missing data.

In this framework, we investigate **Nash implementability** under **complete information**. We describe *situations* in which the planner (she) infers that she can

 elicit the relevant information about the association between the states of the economy and the payoff-relevant states from the individuals (he) unanimously, and

use this information to implement the given collective goal.

X is the finite set of alternatives; X denotes the set of all non-empty subsets of X; N denotes the finite society.

To model the disparity in knowledge, we adopt the following:

- $\Omega$  is the set of *payoff-relevant states*;
- $\Theta$  is the set of the *states of the economy*;
- The *identification function* is a mapping  $\pi^* : \Theta \to \Omega$ ;

►  $R_i^{\omega} \subset X \times X$  denotes the *preferences* of agent  $i \in N$  at  $\omega \in \Omega$ ;  $(R_i^{\omega})_{i \in N, \omega \in \Omega}$  is in one-to-one correspondence with  $\Omega$ . Moreover,  $L_i^{\omega}(x) \equiv \{y \mid x R_i^{\omega} y\}; \mathbb{L}_i^{\omega}(x) \equiv \{S \in \mathcal{X} \mid S \subset L_i^{\omega}(x) \text{ and } x \in S\}.$  The information and knowledge requirements of our model are:

- (*i*) the planner knows  $N, X, \Omega, \Theta$ , and  $f : \Theta \to \mathcal{X}$ ; and
- (ii) N, X,  $\Omega$ ,  $\Theta$ ,  $\pi^* : \Theta \to \Omega$ ,  $f : \Theta \to \mathcal{X}$ , and the realized state of the economy  $\theta \in \Theta$  are common knowledge among the individuals; and
- (*iii*) items (*i*) and (*ii*) are common knowledge among the individuals and the planner.

The essence of the asymmetry of information between the planner and the individuals involves the identification function  $\pi^*$  and the realized state of the economy  $\theta$ .

### Nash Implementation

- The social choice correspondence (SCC) is given by  $f : \Theta \to \mathcal{X}$ .
- A mechanism is  $\mu = (A, g)$  where
  - $A_i$  is *i*'s set of actions with  $A \equiv \times_{i \in \mathbb{N}} A_i$  and  $A_{-i} \equiv \times_{j \neq i} A_j$ ,
  - $g: A \to X$  is the **outcome function**.
  - Given  $a_{-i} \in A_{-i}$ , i's opportunity set is  $O_i^{\mu}(a_{-i}) \equiv g(A_i, a_{-i})$ .
- a\* ∈ A is a Nash equilibrium (NE) of μ at ω ∈ Ω if g(a\*) ∈ ∩<sub>i∈N</sub>C<sup>ω</sup><sub>i</sub>(O<sup>μ</sup><sub>i</sub>(a\*)), where for any S ∈ X, C<sup>ω</sup><sub>i</sub>(S) ≡ {x ∈ S | xR<sup>ω</sup><sub>i</sub>y, ∀y ∈ S}. NE<sup>μ</sup>(θ) consists of x ∈ X such that there is a\* ∈ A with g(a\*) = x and a\* is a Nash equilibrium of μ at π\*(θ) ∈ Ω.
- An SCC f is Nash implementable by  $\mu$  if  $\forall \theta \in \Theta$ ,  $f(\theta) = NE^{\mu}(\theta)$ .

#### Definition

A profile of sets  $\mathbf{S} \equiv (S_i(x, \theta))_{i \in N, \ \theta \in \Theta, \ x \in f(\theta)}$  is <u>rational-consistent</u> with the given SCC  $f : \Theta \rightarrow \mathcal{X}$  if

(i)  $\forall i \in N, \forall \theta \in \Theta, \forall x \in f(\theta), S_i(x, \theta) \in \mathbb{L}_i^{\pi^*(\theta)}(x)$ ; and

(*ii*) If 
$$x \in f(\theta) \setminus f(\tilde{\theta})$$
, then  $\exists j \in N$  s.t.  $S_j(x, \theta) \notin \mathbb{L}_j^{\pi^*(\tilde{\theta})}(x)$ .

S(f) denotes the set of profiles of sets that are rational-consistent with f.

Rational-consistency constitutes a variant of monotonicity of Maskin (1999) and the rational version of consistency of de Clippel (2014).

In words, a profile of sets **S** is rational-consistent with a given SCC f, if

- (*i*) for every individual *i* and state of the economy  $\theta$  and alternative *x* in  $f(\theta)$ , *x* is one of the best alternatives according to  $R_i^{\pi^*(\theta)}$  in the set  $S_i(x, \theta)$ ; and
- (ii) if x is f-optimal at  $\theta$  but not at  $\tilde{\theta}$ , then there exists  $j \in N$  such that x is not among the best alternatives according to  $R_i^{\pi^*(\tilde{\theta})}$  in  $S_j(x, \theta)$ .

If the planner knows that the SCC  $f : \Theta \to \mathcal{X}$  is Nash implementable, then the planner infers that  $\mathcal{S}(f) \neq \emptyset$  without necessarily knowing the full specification of sets that appear in  $\mathcal{S}(f)$ .

### Significance of the theorem:

► This result is a reevaluation of the necessity theorems of

- Maskin (1999) and
- de Clippel (2014)

related to the knowledge inferred by a completely ignorant planner.

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### Sketch of the Proof:

Suppose the planner knows that μ<sup>\*</sup> implements SCC f. Then, she infers that ∀θ and ∀x ∈ f(θ) there is an NE a<sup>x</sup> s.t. g(a<sup>x</sup>) = x.

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- The planner does not know  $\pi^*(\theta)$  and may be uncertain about  $a^x$  if  $\mu^*$  delivers x via at least two action profiles. Still, she infers that

$$x \in \bigcap_{i \in \mathbb{N}} C_i^{\pi^*(\theta)}(O_i^{\mu^*}(a_{-i}^{\mathsf{x}})).$$
(1)

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- The planner does not know π\*(θ) and may be uncertain about a<sup>x</sup> if μ\* delivers x via at least two action profiles. Still, she infers that

$$x \in \bigcap_{i \in \mathbb{N}} C_i^{\pi^*(\theta)}(O_i^{\mu^*}(a_{-i}^x)).$$
(1)

► The planner considers inferences about  $\mathbf{S}^{\mu^*} \equiv (S_i^{\mu^*}(x,\theta))_{i,\theta,x\in f(\theta)}$ , where  $S_i^{\mu^*}(x,\theta) = O_i^{\mu^*}(a_{-i}^x)$ , without knowing its full specification.

If the planner knows that the SCC  $f : \Theta \to \mathcal{X}$  is Nash implementable, then the planner infers that  $\mathcal{S}(f) \neq \emptyset$  without necessarily knowing the full specification of sets that appear in  $\mathcal{S}(f)$ .

### Sketch of the Proof:

- ▶ Then, thanks to (1) the planner infers that  $\mathbf{S}^{\mu^*}$  is s.t.  $x \in \bigcap_{i \in \mathbb{N}} C_i^{\pi^*(\theta)}(S_i^{\mu^*}(x, \theta)) \Rightarrow S_i^{\mu^*}(x, \theta) \in \mathbb{L}_i^{\pi^*(\theta)}(x), \forall i \in \mathbb{N}.$
- So, the planner deduces that S<sup>µ\*</sup> satisfies (i) of rational-consistency even though she does not know its full specification.

If the planner knows that the SCC  $f : \Theta \to \mathcal{X}$  is Nash implementable, then the planner infers that  $\mathcal{S}(f) \neq \emptyset$  without necessarily knowing the full specification of sets that appear in  $\mathcal{S}(f)$ .

### Sketch of the Proof:

• If the planner knows that  $x \in f(\theta) \setminus f(\tilde{\theta})$ , she infers that  $S_i^{\mu^*}(x, \theta) \in L_i^{\pi^*(\tilde{\theta})}(x), \forall i \in N$ 

(2)

would imply an impasse:

- The planner contemplating on S<sup>μ\*</sup>, without knowing its full specification, infers that (2) implies a<sup>x</sup> is an NE at π<sup>\*</sup>(θ).
- As μ\* Nash implements f, she deduces that x would be in f(θ̃); a contradiction.

If the planner knows that the SCC  $f : \Theta \to \mathcal{X}$  is Nash implementable, then the planner infers that  $\mathcal{S}(f) \neq \emptyset$  without necessarily knowing the full specification of sets that appear in  $\mathcal{S}(f)$ .

#### Implications:

- ► The planner knowing the existence of a profile rational-consistent with the given SCC  $f : \Theta \to \Omega$ , constitutes the minimal information
  - $\blacksquare$  about the association between  $\Theta$  and  $\Omega$
  - in conjunction with the Nash implementability of *f*.
- That is why the planner's knowledge of S(f) ≠ Ø can be regarded as a *feasibility* requirement for the Nash implementability of f.
- So, sufficiency has to involve the planner's knowledge of  $S(f) \neq \emptyset$ .

If the planner knows that the SCC  $f : \Theta \to \mathcal{X}$  is Nash implementable, then the planner infers that  $\mathcal{S}(f) \neq \emptyset$  without necessarily knowing the full specification of sets that appear in  $\mathcal{S}(f)$ .

#### Implications:

- Even if the planner were to know  $S(f) \neq \emptyset$ , she does not know  $\pi^*$ .
- She needs to know the full specification of a rational-consistent profile S ∈ S(f) to design mechanisms that can implement f in NE.
- We consider mechanisms in which the planner *asks* agents' help.
- We show that she can elicit a rational-consistent profile S from the society unanimously with the help of a sympathizer.

The notion of sympathy is defined for

- mechanisms involving the announcements of a profile of choice sets
- by modifying partial honesty of Dutta and Sen (2012) so that
- ▶ it involves only announcements of profiles of sets and not states.

To define the notion of sympathy for any given SCC  $f: \Theta \rightarrow \Omega$  consider

• guidance mechanisms  $\mathcal{M}^{S}$  consisting of  $\mu^{S} = (A^{S}, g^{S})$  where  $A_{i}^{S} = S \times M_{i}^{S}$  for all  $i \in N$  where S is given by  $\{\mathbf{S} = (S_{i}(x, \theta))_{i, \theta, x \in f(\theta)} | \forall i \in N, \forall \theta \in \Theta, \forall x \in f(\theta), x \in S_{i}(x, \theta)\},\$ and  $M_{i}^{S}$  is a message set of  $i \in N$ .

• We note that 
$$\mathcal{S}(f) \subset \mathcal{S}$$
.

An action of individual *i* in a guidance mechanism  $\mu^{S} \in \mathcal{M}^{S}$  is  $a_{i} = (\mathbf{S}, m_{i}) \in \mathcal{S} \times M_{i}$ , and

consists of a **profile** of sets feasible w.r.t. *f* and some **messages**.

# Sympathy

For any  $f : \Theta \to \mathcal{X}$ , any  $\mu \in \mathcal{M}^S$ , and any  $\omega \in \Omega$ , the correspondence  $BR_i^{\omega} : A_{-i} \twoheadrightarrow A_i$  identifies *i*'s **best responses** at  $\omega$  to others' actions.

• If *i* is a sympathizer of *f* at  $\omega \in \Omega$ , then  $\forall a_{-i} \in A_{-i}$ 

(i) 
$$\mathbf{S} \in \mathcal{S}(f)$$
,  $\mathbf{\tilde{S}} \notin \mathcal{S}(f)$ , and  $m_i \in M_i$  implies  $(\mathbf{S}, m_i) \in BR_i^{\omega}(a_{-i})$   
and  $(\mathbf{\tilde{S}}, m_i) \notin BR_i^{\omega}(a_{-i})$  if  
 $g((\mathbf{S}, m_i), a_{-i}) R_i^{\omega} g(a'_i, a_{-i}) \forall a'_i \in A_i$ , and  
 $g((\mathbf{\tilde{S}}, m_i), a_{-i}) R_i^{\omega} g(a''_i, a_{-i}) \forall a''_i \in A_i$ ; and

(ii) in all other cases,

 $a_i \in BR_i^\omega(a_{-i})$  if and only if  $g(a_i, a_{-i}) R_i^\omega g(a_i', a_{-i}) \forall a_i' \in A_i$ .

► If *i* is not a sympathizer of *f* at  $\omega \in \Omega$ , then  $\forall a_{-i} \in A_{-i}$ ,  $a_i \in BR_i^{\omega}(a_{-i})$  if and only if  $g(a_i, a_{-i}) R_i^{\omega} g(a'_i, a_{-i}) \forall a'_i \in A_i$ . Guidance mechanisms involve some messages besides the announcement of a profile of sets for each individual.

A sympathizer of the SCC at a payoff-relevant state is an individual who

- strictly prefers the action that consists of the announcement of a consistent profile of sets coupled with some messages
- to another action which involves the announcement of an inconsistent profile while he continues to send the same messages
- whenever both actions provide this agent's top alternative in his opportunity set given others' actions.
- In all other cases, he is a regular economic agent who chooses as described by his state-contingent preferences.

- We say that the environment satisfies the sympathizer property with respect to SCC f
- if for all  $\omega \in \Omega$ , there is at least one sympathizer of f at  $\omega$ ,
- while the identity of each sympathizer of f at ω is privately known only by himself.

# Nash\* Equilibrium: NE with Sympathy

- Given μ ∈ M, a<sup>\*</sup> ∈ A is a Nash<sup>\*</sup> equilibrium of μ at ω if for all i ∈ N, a<sup>\*</sup><sub>i</sub> ∈ BR<sup>ω</sup><sub>i</sub>(a<sup>\*</sup><sub>-i</sub>), where the best responses are as above.
- Given SCC f, if μ ∈ M \ M<sup>S</sup> or there are no sympathizers of f at ω, then NE of μ at ω and Nash\* equilibrium of μ at ω coincide.
- An SCC f : Θ → X is implementable by a mechanism µ ∈ M in Nash\* equilibrium, if
  - (i) for any  $\theta \in \Theta$  and  $x \in f(\theta)$ , there exists  $a^x \in A$  such that  $g(a^x) = x$  and  $a_i^x \in BR_i^{\pi^*(\theta)}(a_{-i}^x)$  for all  $i \in N$ ; and
  - (ii) for any  $\theta \in \Theta$ ,  $a^* \in A$  with  $a_i^* \in BR_i^{\pi^*(\theta)}(a_{-i}^*)$  for all  $i \in N$  implies  $g(a^*) \in f(\theta)$ .

The <u>economic environment</u> assumption demands that there is some weak form of disagreement in the society at every payoff-relevant state:

For every alternative and for every state,

there are at least two individuals who do not choose that alternative at that state from the set of all alternatives.

This assumption is also used in Bergemann and Morris (2008), Kartik and Tercieux (2012), Barlo and Dalkıran (2020).

Suppose  $n \ge 3$ . Suppose that the planner knows that

- *(i)* the <u>environment is economic</u>, and the <u>sympathizer property</u> holds, and
- (ii) the SCC  $f : \Theta \to \mathcal{X}$  has a <u>rational-consistent</u> profile of sets, i.e.,  $\mathcal{S}(f) \neq \emptyset$ , while she does not necessarily know the full specification of the sets that appear in  $\mathcal{S}(f)$ .

Then, the planner infers that f is Nash<sup>\*</sup> implementable by a guidance mechanism  $\mu \in \mathcal{M}^S$ , and for any  $\theta \in \Theta$  and any Nash<sup>\*</sup> equilibrium  $\bar{a} = (\bar{S}^{(i)}, \bar{m}_i)_{i \in N}$  of  $\mu$  at  $\pi^*(\theta)$ ,

 $\bar{\mathbf{S}}^{(i)} = \mathbf{S}$  for some  $\mathbf{S} \in \mathcal{S}(f)$  for all  $i \in N$ .

If the planner (she) knows that there are least three individuals and

- (*i*) the <u>environment is economic</u>, and the <u>sympathizer property</u> holds, and
- (ii) the SCC f has a <u>rational-consistent</u> profile of sets (the full specification of which she does not know),

then she infers that f is

- Nash implementable by a mechanism that
- elicits the relevant information

about the association between the payoff-relevant states and the states of the economy from the society unanimously, while

the identity of the sympathizer is known only to himself.

### Our Main Result: The Mechanism

▶ *i*'s action is 
$$a_i = (S^{(i)}, \theta^{(i)}, x^{(i)}, k^{(i)}) \in A_i$$
 with  $S^{(i)} \in S$ ,  $\theta^{(i)} \in \Theta$ ,  $x^{(i)} \in X$ , and  $k^{(i)} \in \mathbb{N}$ ; let  $m_i = (\theta^{(i)}, x^{(i)}, k^{(i)})$ .

The <u>outcome function</u> is defined via the rules specified as follows:

Rule 1:
$$g(a) = x$$
for some  $i' \in N$ , and $m_j = (\theta, x, \cdot)$  for all  $j \in N$ with  $x \in f(\theta)$ ,

$$\frac{\text{Rule 2}}{\text{I}}: \quad g(a) = \begin{cases} x' & \text{if } x' \in S_j(x, \theta) \\ \text{where } S_j(x, \theta) = \mathbf{S}|_{j, \theta, x \in f(\theta)}, \\ x & \text{otherwise.} \end{cases}$$

**Rule 3**: 
$$g(a) = x^{(i^*)}$$
 where  
 $i^* = \min\{j \in N \mid k^{(j)} = \max_{i' \in N} k^{(i')}\}$ 

$$\begin{split} &\text{if } \mathbf{S}^{(i)} = \mathbf{S} \text{ for all } i \in N \setminus \{i'\} \\ &\text{for some } i' \in N, \text{ and} \\ &m_i = (\theta, x, \cdot) \text{ for all } i \in N \setminus \{j\} \\ &\text{with } x \in f(\theta), \text{ and} \\ &m_j = (\theta', x', \cdot) \neq (\theta, x, \cdot), \end{split}$$

if  $\mathbf{S}^{(i)} = \mathbf{S}$  for all  $i \in N \setminus \{i'\}$ 

otherwise.

### Our Main Result: Sketch of the Proof

### The arguments behind the proof:

- The planner does not know the identification function  $\pi^* : \Theta \to \Omega$ and hence agents' lower contour sets.
- She uses agents' announcements to construct their opportunity sets whenever announcements of all individuals but one coincide.

Agents' **opportunity sets** are determined by their announcements  $(\mathbf{S}^{(i)})_{i \in N} \in S^N.$ 

- The sympathizer property ensures that all agents announce a rational-consistent profile in any Nash\* equilibrium under Rule 1.
- The economic environment assumption ensures that there is no Nash\* equilibrium under Rules 2 and 3.

- We propose a way to ensure the planner's inference of the existence of a rational-consistent profile. It involves Maskin monotonicity.
- A correspondence φ : Ω → 2<sup>X</sup> is Maskin monotonic if x ∈ φ(ω) and L<sup>ω</sup><sub>i</sub>(x) ⊆ L<sup>ω</sup><sub>i</sub>(x) for all i ∈ N implies x ∈ φ(ω̃), where ω, ω̃ ∈ Ω

•  $2^X$  denotes the set of all (possibly empty) subsets of X.

•  $f_{\Omega}: \Omega \to 2^X$  is an extension of an SCC  $f: \Theta \to \mathcal{X}$  to  $\Omega$  if  $f(\theta) = f_{\Omega}(\pi^*(\theta))$  for all  $\theta \in \Theta$ .



If the planner knows that SCC  $f:\Theta\to \mathcal{X}$ 

has a Maskin monotonic extension even if she does not know the full specification of this extension,

then she infers that  $S(f) \neq \emptyset$  without necessarily knowing the specification of sets that appear in S(f).

- Now, we adopt the convention that
  - a state under complete information is to encompass all the information that is common knowledge among the individuals.
- ► The set of grand states:  $\Sigma \equiv \{(\theta, \omega, \pi) \in \Theta \times \Omega \times \Pi \mid \pi(\theta) = \omega\}$ , with  $\sigma = (\theta, \omega, \pi)$  with  $\pi(\theta) = \omega$  and  $\Pi \equiv \{\pi' \mid \pi' : \Theta \to \Omega\}$ .

• We extend f onto  $\Sigma$  by  $f(\sigma) = f(\theta)$  for all  $\sigma = (\theta, \omega, \pi) \in \Sigma$ .

• The mechanisms with the announcement of a grand state,  $\mathcal{M}^{\Sigma}$ :

• 
$$\mu = (A, g)$$
 with  $A_i = (\sigma^{(i)}, m_i) \in \Sigma \times M_i$ ,  $\forall i \in N$ .

Individuals' best responses at  $\sigma = (\theta, \omega, \pi)$  under partial honesty are:

▶ If *i* is partially honest at  $\sigma = (\theta, \omega, \pi)$ , then  $\forall a_{-i} \in A_{-i}$ 

(i) 
$$\tilde{\sigma} \neq \sigma$$
 and  $m_i, \tilde{m}_i \in M_i$  implies  $(\sigma, m_i) \in BR_i^{\omega}(a_{-i})$  and  
 $(\tilde{\sigma}, \tilde{m}_i) \notin BR_i^{\omega}(a_{-i})$  if  
 $g((\sigma, m_i), a_{-i}) R_i^{\omega} g(a'_i, a_{-i}) \forall a'_i \in A_i$ , and  
 $g((\tilde{\sigma}, \tilde{m}_i), a_{-i}) R_i^{\omega} g(a''_i, a_{-i}) \forall a''_i \in A_i$ ; and

(ii) in all other cases,

 $a_i \in BR_i^{\omega}(a_{-i})$  if and only if  $g(a_i, a_{-i}) R_i^{\omega} g(a'_i, a_{-i}) \forall a'_i \in A_i$ .

▶ If *i* is **not partially honest** at  $\sigma$ , then  $\forall a_{-i} \in A_{-i}$ ,  $a_i \in BR_i^{\omega}(a_{-i})$  if and only if  $g(a_i, a_{-i}) R_i^{\omega} g(a'_i, a_{-i}) \forall a'_i \in A_i$ .  $\mathcal{M}^\Sigma$  consists of mechanisms that involve some messages besides the announcement of a grand state for each individual.

A partially honest individual at the realized grand state

- strictly prefers the action that consists of the announcement of the realized grand state coupled with some messages
- to another action which involves the announcement of a different grand state while sending some other messages
- whenever both actions provide this agent's top alternative in his opportunity set given others' actions.
- In all other cases, he is a regular economic agent who chooses as described by his state-contingent preferences.

Theorem 1 of Dutta and Sen (2012) implies:

If the planner knows that for every state  $\sigma\in\Sigma$ 

- there is a partially honest individual at σ (even if she does not know the identity of this agent) for all σ ∈ Σ, and that
- the SCC  $f: \Theta \rightarrow \mathcal{X}$  satisfies the no-veto property,

then she infers that

f is Nash\* implementable and in every such equilibrium all but one announce a grand set *aligned* with the realized grand set.

### Weak Partial Honesty

Next, we define **weak partial honesty** to compare with sympathy s.t. the agent at hand is partially honest with respect to  $\pi$  but not  $(\theta, \omega)$ :

Agents' **best responses** at  $\sigma = (\theta, \omega, \pi^*)$  under weak partial honesty are

▶ If *i* is weakly partially honest at  $\sigma = (\theta, \omega, \pi^*)$ , then  $\forall a_{-i} \in A_{-i}$ 

(i) 
$$\tilde{\sigma} = (\tilde{\theta}, \tilde{\omega}, \pi^*)$$
 and  $\hat{\sigma} = (\hat{\theta}, \hat{\omega}, \hat{\pi})$  with  $\hat{\pi} \neq \pi^*$  and  $\tilde{m}_i, \hat{m}_i \in M_i$   
implies  $(\tilde{\sigma}, \tilde{m}_i) \in BR_i^{\omega}(a_{-i})$  and  $(\hat{\sigma}, \hat{m}_i) \notin BR_i^{\omega}(a_{-i})$  if  
 $g((\tilde{\sigma}, \tilde{m}_i), a_{-i}) R_i^{\omega} g(a'_i, a_{-i}) \forall a'_i \in A_i$ , and  
 $g((\hat{\sigma}, \hat{m}_i), a_{-i}) R_i^{\omega} g(a''_i, a_{-i}) \forall a''_i \in A_i$ ; and

(ii) in all other cases,

 $a_i \in BR_i^{\omega}(a_{-i})$  if and only if  $g(a_i, a_{-i}) R_i^{\omega} g(a'_i, a_{-i}) \forall a'_i \in A_i$ .

▶ If *i* is **not partially honest** at  $\sigma$ , then  $\forall a_{-i} \in A_{-i}$ ,  $a_i \in BR_i^{\omega}(a_{-i})$  if and only if  $g(a_i, a_{-i}) R_i^{\omega} g(a'_i, a_{-i}) \forall a'_i \in A_i$ . A weakly partially honest agent at the realized grand state, where the realized (true) association between the states of the economy and payoff-relevant states is  $\pi^*$  as in our setup,

- strictly prefers the action that consists of the announcement of the realized association, π<sup>\*</sup>, coupled with some messages
- ► to another action which involves the announcement of a different association,  $\pi \neq \pi^*$ , while sending some other messages
- whenever both actions provide this agent's top alternative in his opportunity set given others' actions.
- In all other cases, he is a regular economic agent who chooses as described by his state-contingent preferences.

# Weak Partial Honesty vs. Strong Sympathy

If the realized association between the states of the economy  $\Theta$  and payoff-relevant states  $\Omega$  is  $\pi^*$  as in our setup, then

the definition of a weakly partially honest individual resembles our definition of a strong sympathizer.

Given a guidance mechanism  $\mu^{S} = (A^{S}, g^{S})$  the **best responses** of a **strong sympathizer** *i* of *f* at  $\omega$  are such that if  $\forall a_{-i}$ ,

(i) S ∈ S(f), Ŝ ∉ S(f), and m<sub>i</sub>, m̂<sub>i</sub> ∈ M<sup>S</sup><sub>i</sub> implies (S, m<sub>i</sub>) ∈ BR<sup>ω</sup><sub>i</sub>(a<sub>-i</sub>) and (Ŝ, m̂<sub>i</sub>) ∉ BR<sup>ω</sup><sub>i</sub>(a<sub>-i</sub>) if
g<sup>S</sup>((S, m<sub>i</sub>), a<sub>-i</sub>)R<sup>ω</sup><sub>i</sub>g<sup>S</sup>(a'<sub>i</sub>, a<sub>-i</sub>) for all a'<sub>i</sub> ∈ A<sub>i</sub>, and
g<sup>S</sup>((Ŝ, m̂<sub>i</sub>), a<sub>-i</sub>)R<sup>ω</sup><sub>i</sub>g<sup>S</sup>(a''<sub>i</sub>, a<sub>-i</sub>) for all a''<sub>i</sub> ∈ A<sub>i</sub>; and
(ii) otherwise, a<sub>i</sub> ∈ BR<sup>ω</sup><sub>i</sub>(a<sub>-i</sub>) iff g<sup>S</sup>(a<sub>i</sub>, a<sub>-i</sub>)R<sup>ω</sup><sub>i</sub>g<sup>S</sup>(a'<sub>i</sub>, a<sub>-i</sub>) ∀a'<sub>i</sub> ∈ A<sub>i</sub>.

If  $i \in N$  is **not a strong sympathizer** of f at  $\omega$ , then  $a_i \in BR_i^{\omega}(a_{-i})$  iff  $g^{S}(a_i, a_{-i})R_i^{\omega}g^{S}(a'_i, a_{-i})$  for all  $a'_i \in A_i$ .

# Strong Sympathy (in words)

Guidance mechanisms involve some messages besides the announcement of a profile of sets for each individual. A **strong sympathizer** of the SCC at a payoff-relevant state is an individual who

- strictly prefers the action that consists of the announcement of a consistent profile of sets coupled with some messages
- to another action which involves the announcement of an inconsistent profile along with some other messages
- whenever both actions provide this agent's top alternative in his opportunity set given others' actions.
- In all other cases, he is a regular economic agent who chooses as described by his state-contingent preferences.

We note that every **strong sympathizer** is a **sympathizer**.

# Weak Partial Honesty vs. Strong Sympathy

If the realized association between the states of the economy  $\Theta$  and payoff-relevant states  $\Omega$  is  $\pi^*$  as in our setup, then

the definition of a weakly partially honest individual resembles our definition of a strong sympathizer.

#### **Observations:**

- Interchanging π<sup>\*</sup> with S ∈ S(f) and π̂ with Ŝ ∉ S(f) displays parallels between strong sympathy of f at π<sup>\*</sup>(θ) and weak partial honesty at σ = (θ, ω, π<sup>\*</sup>).
- If the planner is informed of π\*, then she can construct the set of rational-consistent profiles S(f).
- But, she cannot necessarily identify π<sup>\*</sup> uniquely if she is informed of an element S in S(f).

# Weak Partial Honesty vs. Strong Sympathy

If the realized association between the states of the economy  $\Theta$  and payoff-relevant states  $\Omega$  is  $\pi^*$  as in our setup, then

the definition of a weakly partially honest individual resembles our definition of a strong sympathizer.

#### **Observations:**

Thus, in our construct, to implement a given SCC,

the **extent of information** the planner seeks to elicit with the **help** of a **strong sympathizer** is

#### less than

the extent of information the planner obtains thanks to a weakly partially honest individual.

We extend our setting and results to the **<u>behavioral domain</u>**:

- The choice of *i* at  $\omega \in \Omega$  is  $C_i^{\omega} : \mathcal{X} \to \mathcal{X}$  s.t.  $C_i^{\omega}(S) \subset S, \forall S \in \mathcal{X}$ .
- A profile  $\mathbf{S} := (S_i(x, \theta))_{i, \theta, x \in f(\theta)}$  is **consistent** with the given SCC  $f : \Theta \to \mathcal{X}$  if

(i) 
$$\forall \theta \in \Theta, \forall x \in f(\theta), x \in \cap_{i \in N} C_i^{\pi^*(\theta)}(S_i(x, \theta));$$
 and  
(ii)  $x \in f(\theta) \setminus f(\theta')$  implies  $x \notin \cap_{i \in N} C_i^{\pi^*(\theta')}(S_i(x, \theta)).$ 

S(f) denotes the set of all profiles of sets that are consistent with f.

Using de Clippel's necessity result and similar arguments leading to our necessity theorem, enable us to conclude the following:

If the planner knows that f is behavioral Nash implementable, then she infers that S(f) ≠ Ø without necessarily knowing the full specification of sets that appear in S(f). For any  $f: \Theta \to \mathcal{X}$ , any  $\mu \in \mathcal{M}^{S}$ , and any  $\omega \in \Omega$ , the correspondence  $BR_{i}^{\omega}: A_{-i} \twoheadrightarrow A_{i}$  identifies *i*'s **behavioral best responses** at  $\omega$  to  $a_{-i}$ .

▶ If *i* is a **behavioral sympathizer** of *f* at  $\omega$ , then  $\forall a_{-i}$ 

(i) 
$$\mathbf{S} \in \mathcal{S}(f)$$
,  $\tilde{\mathbf{S}} \notin \mathcal{S}(f)$ , and  $m_i \in M_i$  implies  $(\mathbf{S}, m_i) \in BR_i^{\omega}(a_{-i})$   
and  $(\tilde{\mathbf{S}}, m_i) \notin BR_i^{\omega}(a_{-i})$  if  
 $g((\mathbf{S}, m_i), a_{-i}), g((\tilde{\mathbf{S}}, m_i), a_{-i}) \in C_i^{\omega}(O_i^{\mu}(a_{-i}); and$ 

(ii) in all other cases,

 $a_i \in BR_i^{\omega}(a_{-i})$  if and only if  $g(a_i, a_{-i}) \in C_i^{\omega}(O_i^{\mu}(a_{-i}))$ .

▶ If *i* is **not** a **behavioral sympathizer** of *f* at  $\omega$ , then  $\forall a_{-i}$  $a_i \in BR_i^{\omega}(a_{-i})$  if and only if  $g(a_i, a_{-i}) \in C_i^{\omega}(O_i^{\mu}(a_{-i}))$ . For any  $f: \Theta \to \mathcal{X}$ , any  $\mu \in \mathcal{M}^{S}$ , and any  $\omega \in \Omega$ , the correspondence  $BR_{i}^{\omega}: A_{-i} \twoheadrightarrow A_{i}$  identifies *i*'s **behavioral best responses** at  $\omega$  to  $a_{-i}$ .

▶ If *i* is a strong behavioral sympathizer of *f* at  $\omega$ , then  $\forall a_{-i}$ 

(i) 
$$\mathbf{S} \in \mathcal{S}(f)$$
,  $\mathbf{\tilde{S}} \notin \mathcal{S}(f)$ , and  $m_i, \tilde{m}_i \in M_i$  implies  
 $(\mathbf{S}, m_i) \in BR_i^{\omega}(a_{-i})$  and  $(\mathbf{\tilde{S}}, \tilde{m}_i) \notin BR_i^{\omega}(a_{-i})$  if  
 $g((\mathbf{S}, m_i), a_{-i}), g((\mathbf{\tilde{S}}, \tilde{m}_i), a_{-i}) \in C_i^{\omega}(O_i^{\mu}(a_{-i});$  and

(ii) in all other cases,

 $a_i \in BR_i^{\omega}(a_{-i})$  if and only if  $g(a_i, a_{-i}) \in C_i^{\omega}(O_i^{\mu}(a_{-i}))$ .

▶ If *i* is not a strong behavioral sympathizer of *f* at  $\omega$ , then  $\forall a_{-i}$  $a_i \in BR_i^{\omega}(a_{-i})$  if and only if  $g(a_i, a_{-i}) \in C_i^{\omega}(O_i^{\mu}(a_{-i}))$ . The environment satisfies the **behavioral sympathizer property** with respect to SCC *f* if for all  $\omega \in \Omega$ ,

- there is at least **one behavioral sympathizer** of f at  $\omega$ ,
- while the identity of each behavioral sympathizer of f at ω is privately known only by himself.

The environment satisfies the **behavioral sympathizer property** with respect to SCC *f* if for all  $\omega \in \Omega$ ,

- there is at least **one behavioral sympathizer** of f at  $\omega$ ,
- while the identity of each behavioral sympathizer of f at ω is privately known only by himself.

The environment satisfies the strong behavioral sympathizer property with respect to SCC f if for all  $\omega \in \Omega$ ,

- there is are least two strong behavioral sympathizers of f at  $\omega$ ,
- while the identity of each strong behavioral sympathizer of f at ω is privately known only by himself.

# Societal Agreement Conditions

We say that

- (*i*) the environment features **societal non-satiation** if for all  $\omega$  and all x, there is an individual *i* s.t.  $x \notin C_i^{\omega}(X)$ .
- (*ii*) the **behavioral economic environment** assumption holds if for all  $\omega$  and all x, there are i, j with  $i \neq j$  s.t.  $x \notin C_i^{\omega}(X) \cup C_i^{\omega}(X)$ .
- (iii) an SCC  $f : \Theta \to \mathcal{X}$  satisfies the **behavioral no-veto property** if for all  $\theta$ ,  $x \in \bigcap_{i \in N \setminus \{j\}} C_i^{\pi^*(\theta)}(X)$  for some  $j \in N$  implies  $x \in f(\theta)$ .

We remark that

- Behavioral economic environment implies societal non-satiation.
- Every SCC satisfies the behavioral no-veto property vacuously whenever the behavioral economic environment assumption holds.
- When the meaning is clear, we do not spell out the 'behavioral' label of our notions and in our results.

# Sufficiency in Noneconomic Environments

#### Theorem

Let  $n \geq 3$  and the SCC  $f : \Theta \to \mathcal{X}$  be given. Suppose that

- (*i*) the planner knows that societal non-satiation and the strong sympathizer property hold, and
- (ii) without necessarily knowing the full specification of sets that appear in S(f), the planner knows that
  - (ii.1)  $S(f) \neq \emptyset$ , i.e. f has a consistent profile of sets and that
  - (*ii*.2) *f* satisfies the **no-veto property**.

Then, the planner infers that f is Nash<sup>\*</sup> implementable by a guidance mechanism  $\mu \in \mathcal{M}^S$ , and for any state of the economy  $\theta \in \Theta$  and any Nash<sup>\*</sup> equilibrium  $\bar{a} = (\bar{\mathbf{S}}^{(i)}, \bar{m}_i)_{i \in N}$  of  $\mu$  at state  $\pi^*(\theta)$ ,

 $\overline{\mathbf{S}}^{(i)} = \mathbf{S}$  for some  $\mathbf{S} \in \mathcal{S}(f)$  for all  $i \in \mathbb{N} \setminus \{j\}$  for some  $j \in \mathbb{N}$ .

# Sufficiency in Noneconomic Environments

If the planner (she) knows that there are least three individuals and

- (*i*) the <u>societal non-satiation</u>, and the <u>strong sympathizer property</u> holds, and
- (ii) f has a <u>rational-consistent</u> profile of sets (the full specification of which she does not know) and satisfies the <u>no-veto property</u>,

then she infers that f is

- Nash implementable by a guidance mechanism that
- elicits the information about consistency

from the society *almost* unanimously, while

the identity of the sympathizer is known only to himself.

### The Mechanism

We use the same <u>mechanism</u>:

i's action is 
$$a_i = (S^{(i)}, \theta^{(i)}, x^{(i)}, k^{(i)}) \in A_i$$
 with  $S^{(i)} \in S$ ,  $\theta^{(i)} \in \Theta$ ,  $x^{(i)} \in X$ , and  $k^{(i)} \in \mathbb{N}$ ; let  $m_i = (\theta^{(i)}, x^{(i)}, k^{(i)})$ .

The **<u>outcome function</u>** is defined via the rules specified as follows:

Rule 1
$$g(a) = x$$
for some  $i' \in N$ , and $m_i = (\theta, x, \cdot)$  for all  $i \in N$ 

$$\frac{\textbf{Rule 2}}{\textbf{Rule 2}}: \quad g(a) = \begin{cases} x' & \text{if } x' \in S_j(x, \theta) \\ & \text{where } S_j(x, \theta) = \textbf{S}|_{j, \theta, x \in f(\theta)} \\ x & \text{otherwise.} \end{cases}$$

Rule 3: 
$$g(a) = x^{(i^*)}$$
 where  
 $i^* = \min\{j \in N \mid k^{(j)} = \max_{i' \in N} k^{(i')}\}$ 

if  $\mathbf{S}^{(i)} = \mathbf{S}$  for all  $i \in N \setminus \{i'\}$ for some  $i' \in N$ , and  $m_j = (\theta, x, \cdot)$  for all  $j \in N$ with  $x \in f(\theta)$ ,

$$\begin{split} &\text{if } \mathbf{S}^{(i)} = \mathbf{S} \text{ for all } i \in N \setminus \{i'\} \\ &\text{for some } i' \in N, \text{ and} \\ &m_i = (\theta, x, \cdot) \text{ for all } i \in N \setminus \{j\} \\ &\text{with } x \in f(\theta), \text{ and} \\ &m_j = (\theta', x', \cdot) \neq (\theta, x, \cdot), \end{split}$$

otherwise.

### The Sketch of the Proof

### The arguments behind the proof:

The planner uses agents' announcements to construct their opportunity sets if announcements of all but one coincide.

Agents' **opportunity sets** are determined by their announcements  $(\mathbf{S}^{(i)})_{i \in N} \in S^N$ .

- The dismissal of the economic environment and the adoption of societal non-satiation coupled with the no-veto property result in new Nash\* equilibria under Rules 1 and 2.
- The sympathizer property does not suffice to ensure the extraction of information about consistency unanimously.
- Now, we need at least two strong sympathizers, and hence the strong sympathizer property, to elicit the information about consistency almost unanimously.

### The arguments behind the proof:

- To see why we need two strong sympathizers, consider the following case under Rule 1 which we have to rule out in Nash\* eq.:
- All i except the odd man out j announce the same profile S ∉ S(f) while the remaining messages of all (including j) coincide and contain θ and x such that x is f-optimal at θ.
- Then, we cannot rule this case out under Rule 1 in Nash\* eq. with only one sympathizer as he could be the odd man out. So, we need another sympathizer announcing S. But that is not enough because:
- This agent has to be a strong sympathizer to obtain a profitable deviation by changing his profile announcement and integer choice. Thus, we also need to strengthen sympathy to strong sympathy.
- Even then there are Nash\* equilibria in which not all, but all except one, announce a consistent profile of sets.

We investigate Nash implementation when the planner is completely ignorant of the association between the states of the economy and individuals' preferences.

We identify conditions ensuring that the planner infers that she can

- elicit the relevant information about the association between the states of the economy and the payoff-relevant states from the society unanimously, and
- use this information to implement the given collective goal.